

1 / 16

FIG. 1

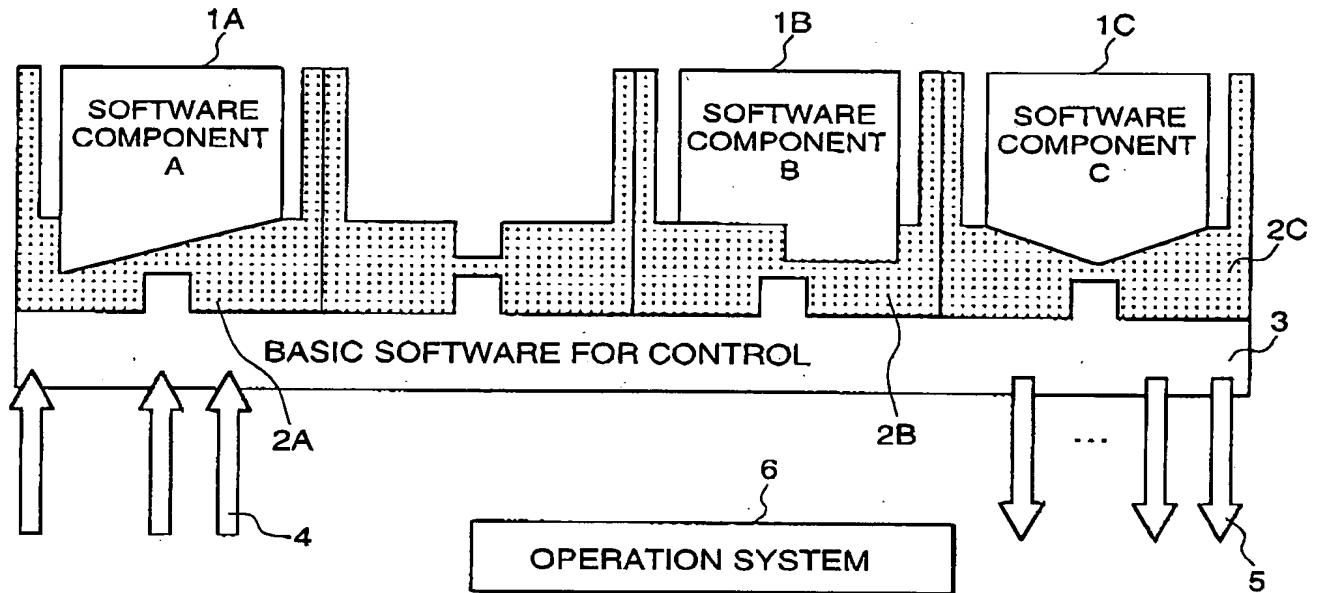
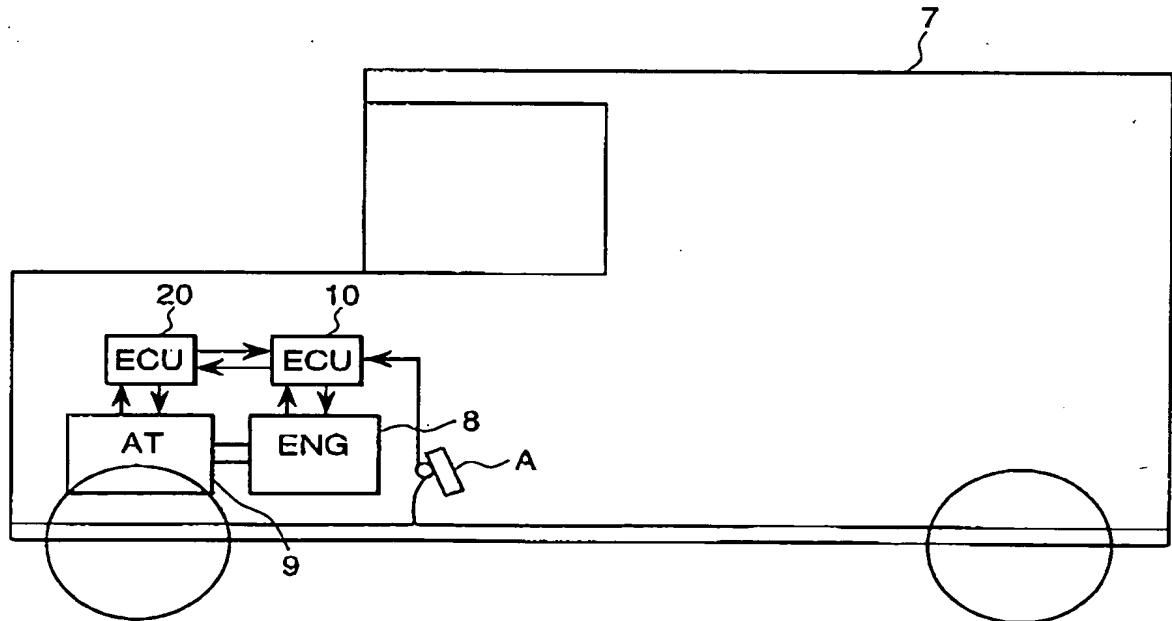
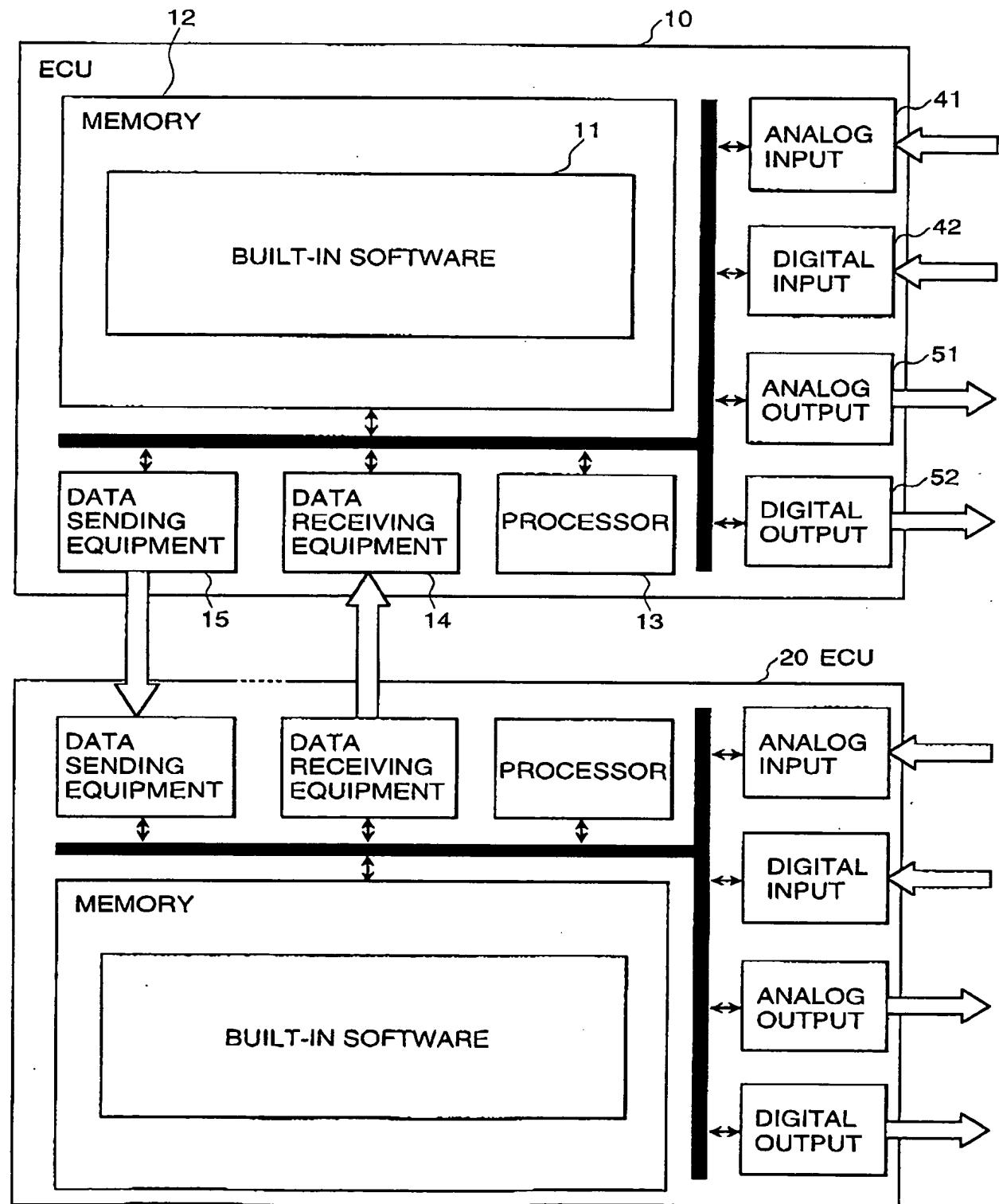


FIG. 2



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FIG. 3



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FIG. 4

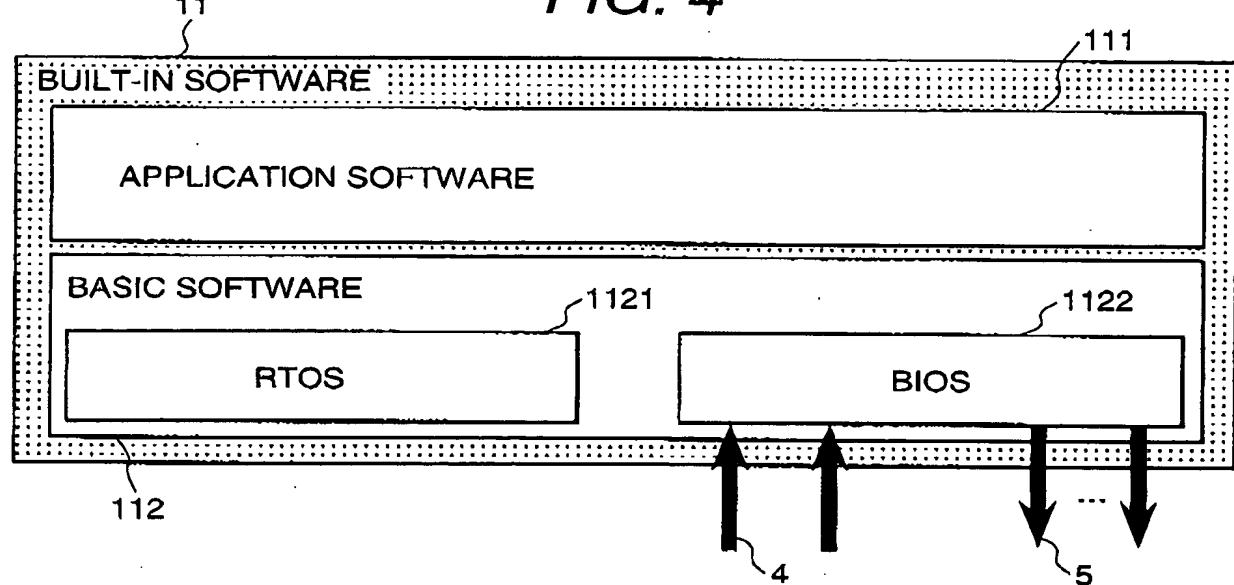
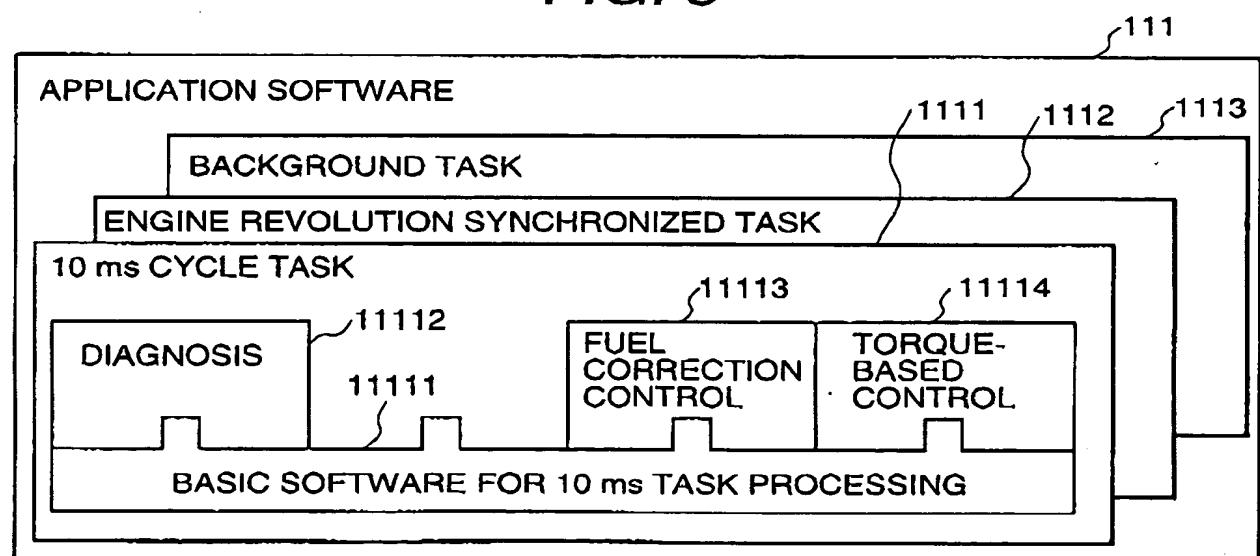


FIG. 5



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FIG. 6

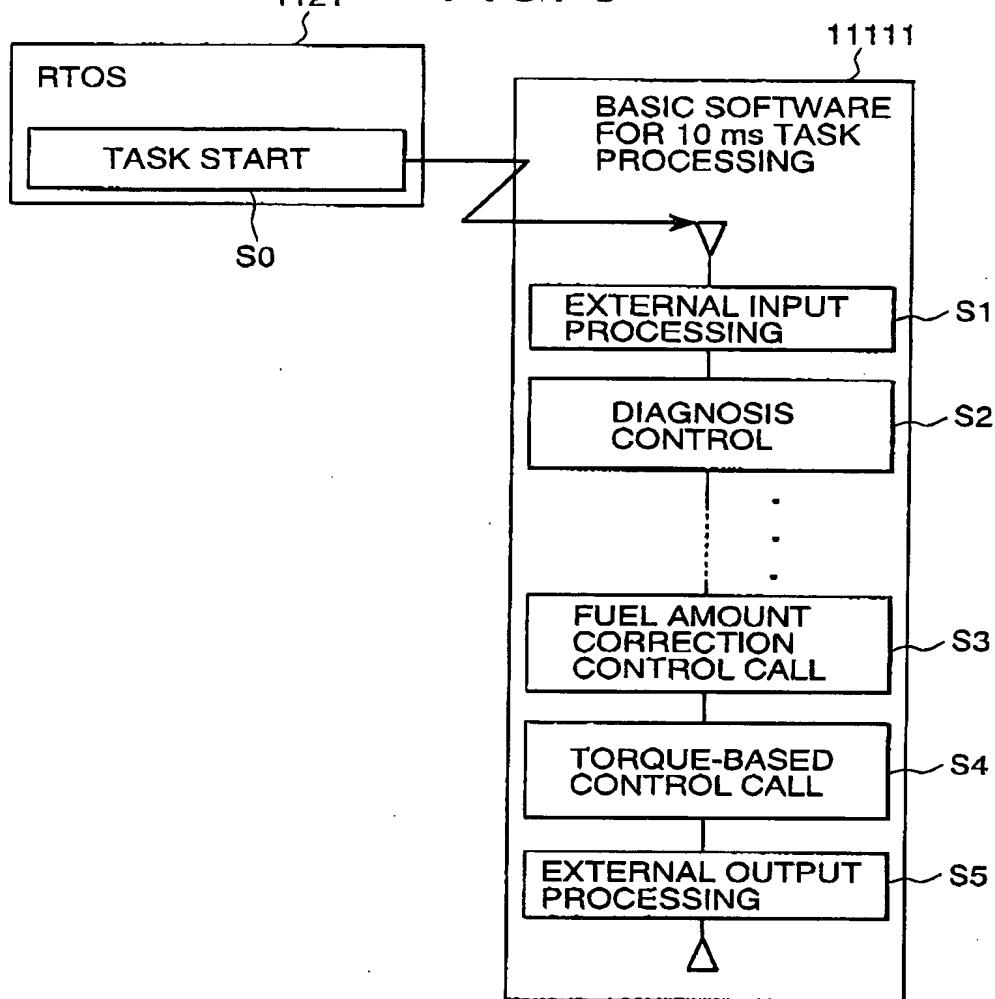
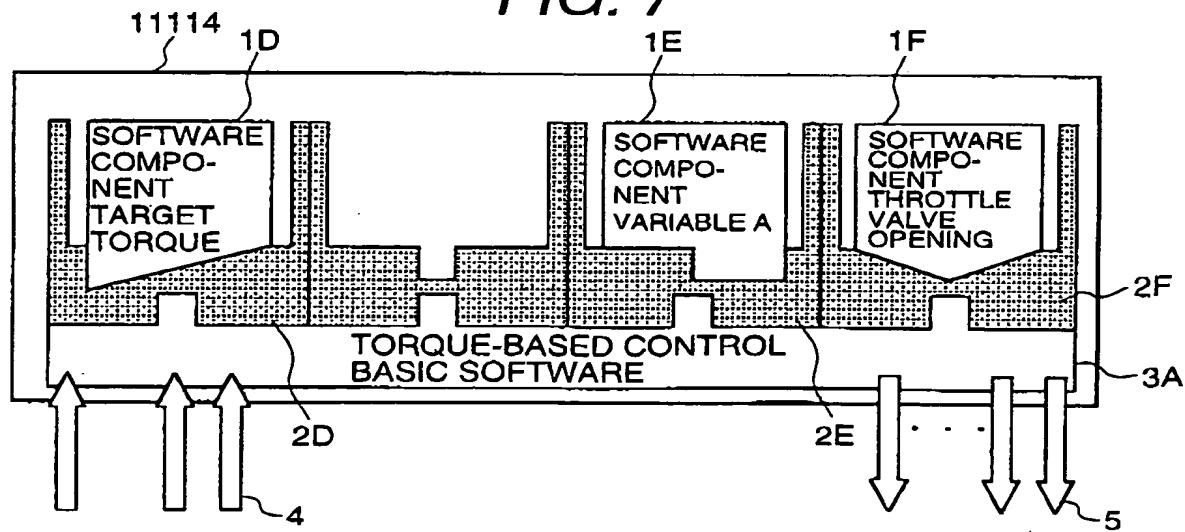


FIG. 7



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FIG. 8

```
extern void TVO_Calculate(unsigned short TargetTorque,  
...,  
    unsigned short Variable_A,  
    unsigned short *TVO  
);  
/* EOF */
```

C11

```
void TVO_Calculate(  
    unsigned short TargetTorque,  
    ...  
    unsigned short Variable_A,  
    unsigned short *TVO  
)  
{  
    ...  
    ...  
    ...  
    *TVO=TargetTorque*Kt+Variable_A*Ka;  
}  
/* EOF */
```

C12

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FIG. 9

```
unsigned short TVO;  
/* EOF*/
```

C21

```
#define TVO_Get() TVO  
extern unsigned short TVO;  
/* EOF*/
```

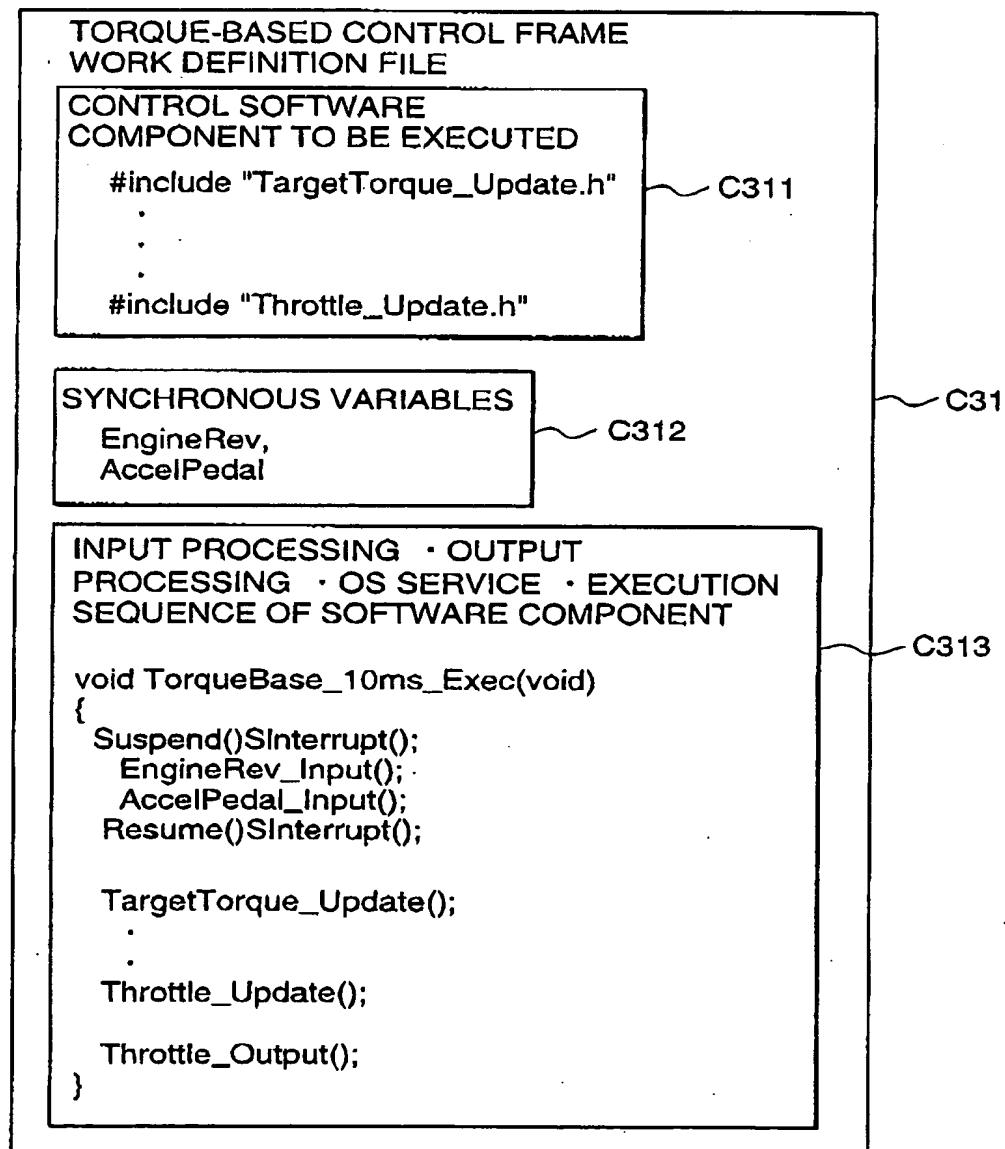
C22

```
#include "TVO.h"  
#include "TargetTorpue.h"  
.  
.  
.  
#include "variableA.h"  
#define TVO_Update() ¥  
{ ¥  
    TVO_Calculate(¥  
    TargetTorque_Get()¥  
    .  
    .  
    .  
    variableA_Get(),¥  
    &TVO¥  
    )¥  
}  
/*EOF*/
```

C23

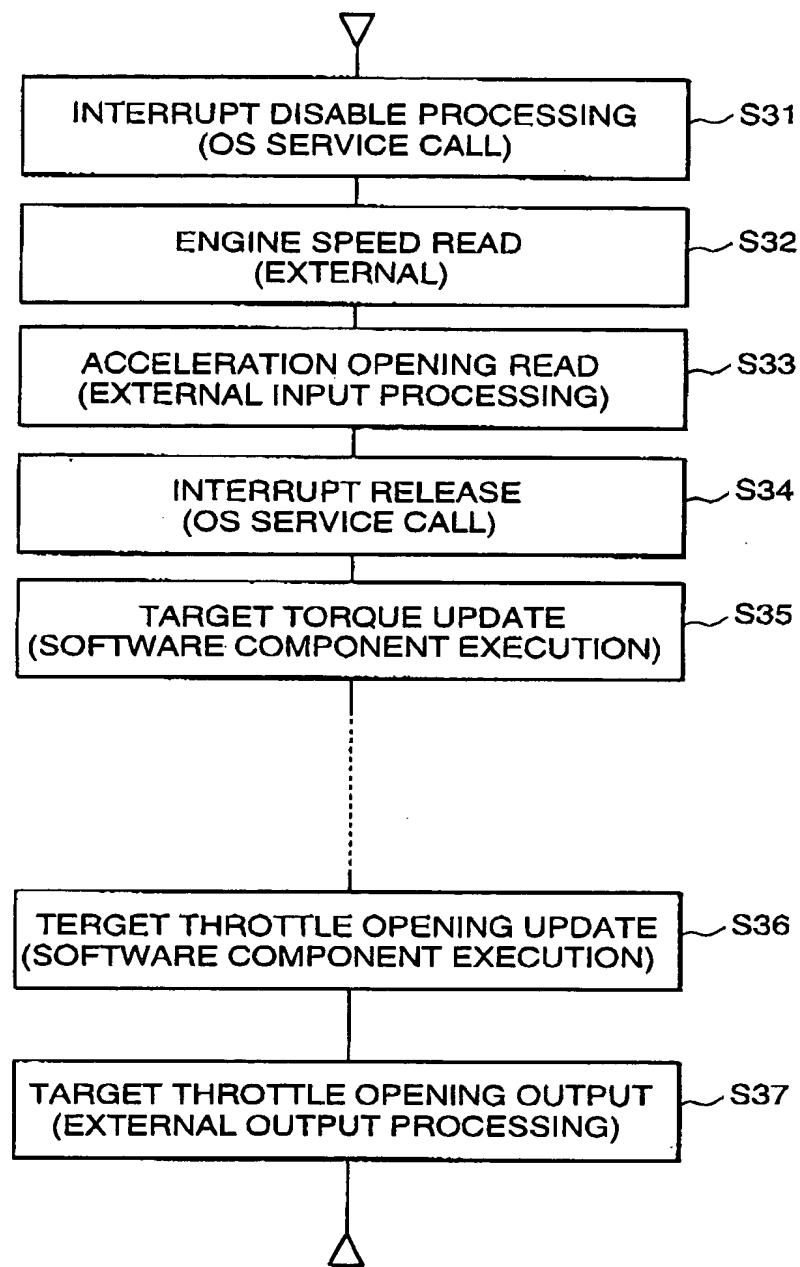
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FIG. 10



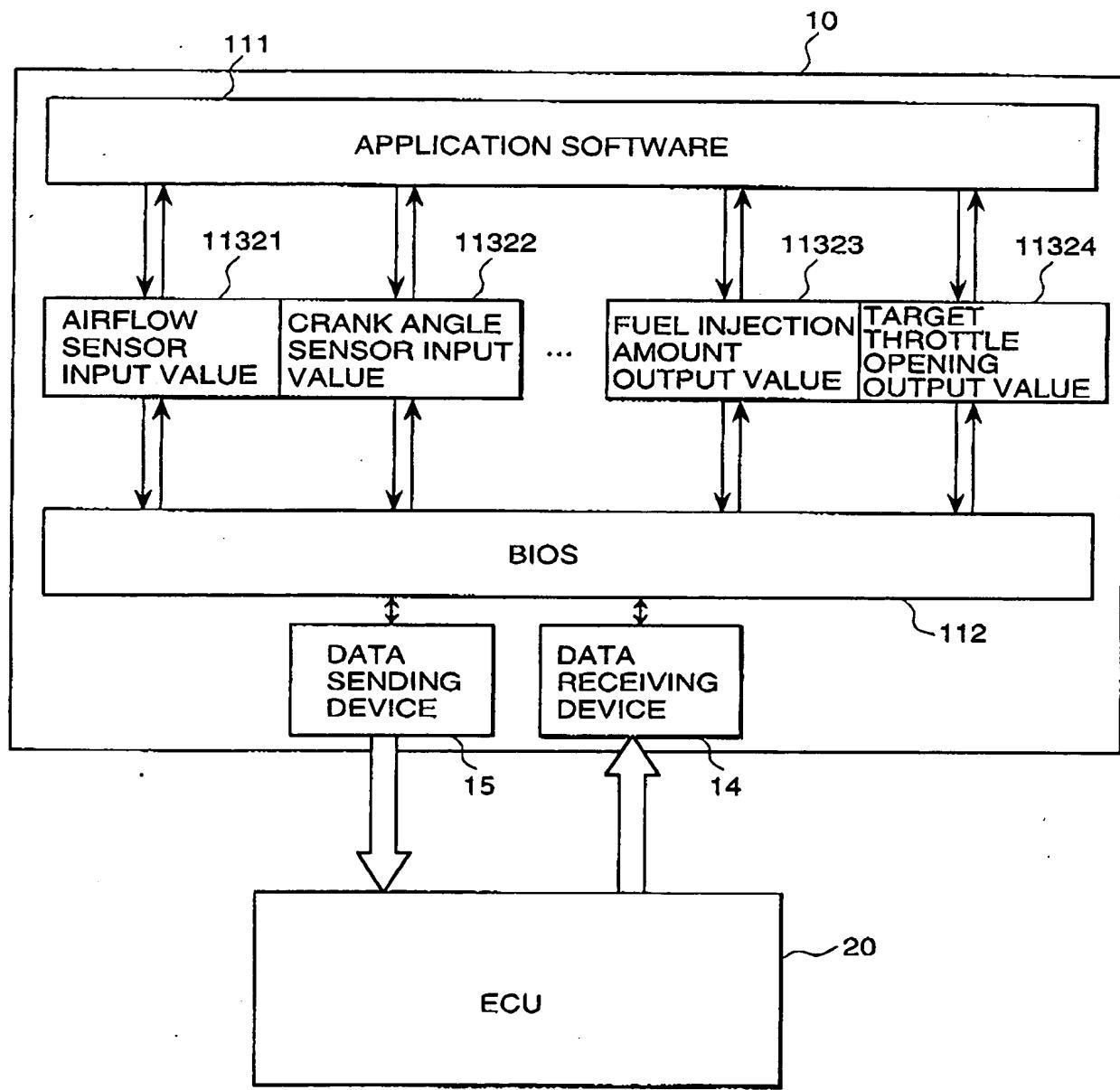
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FIG. 11



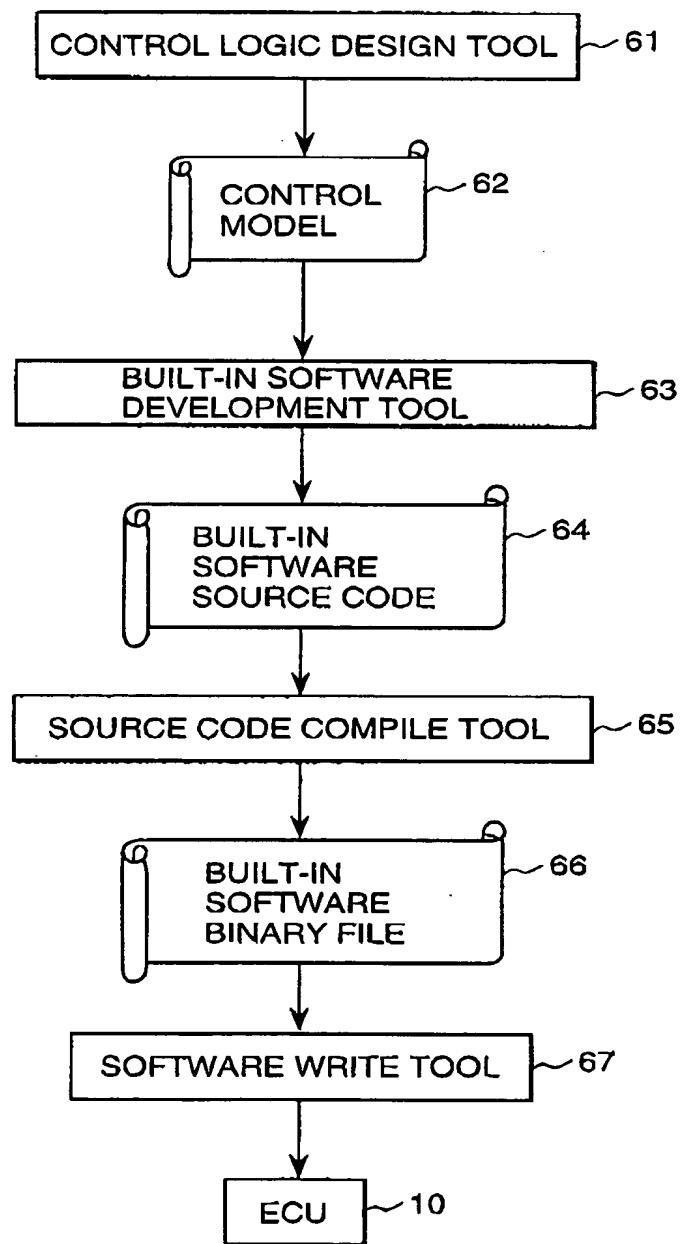
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FIG. 12



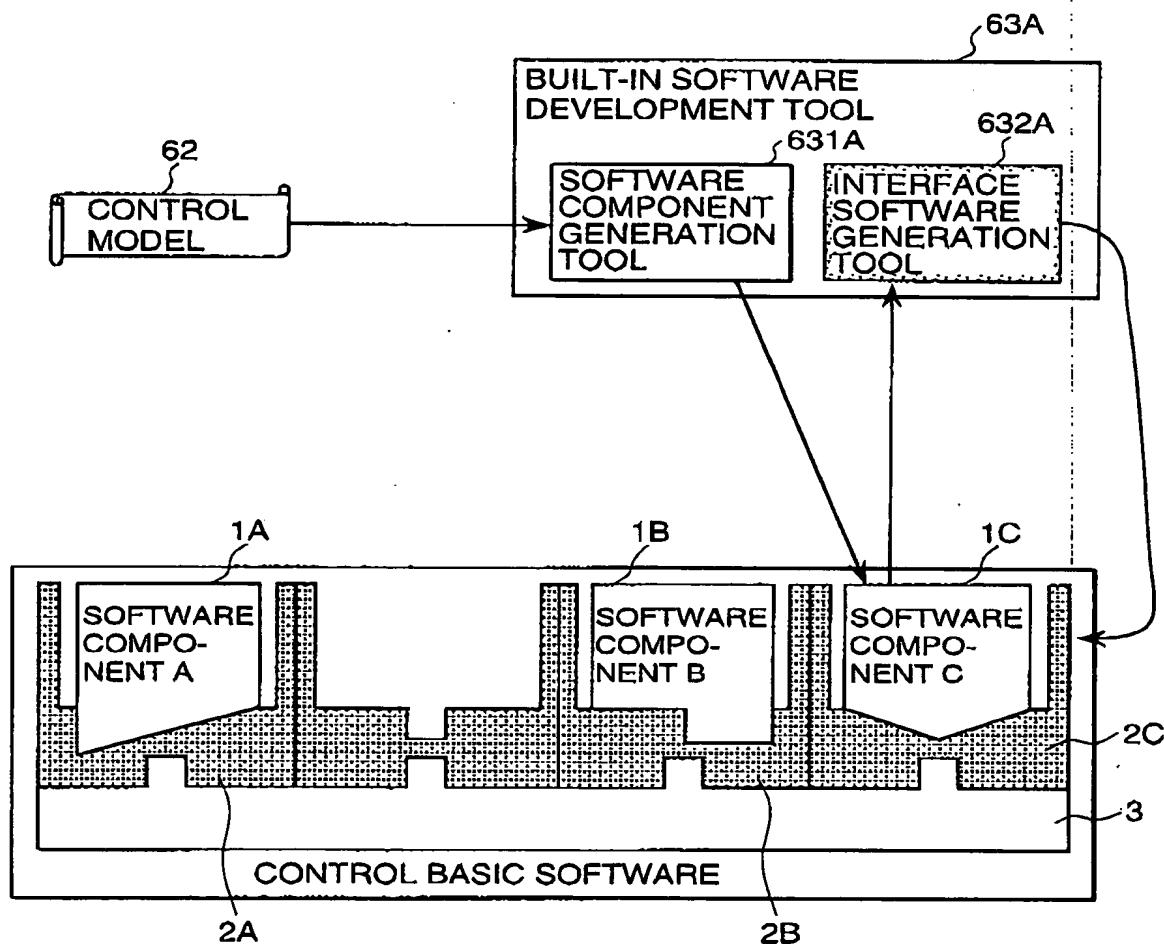
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FIG. 13



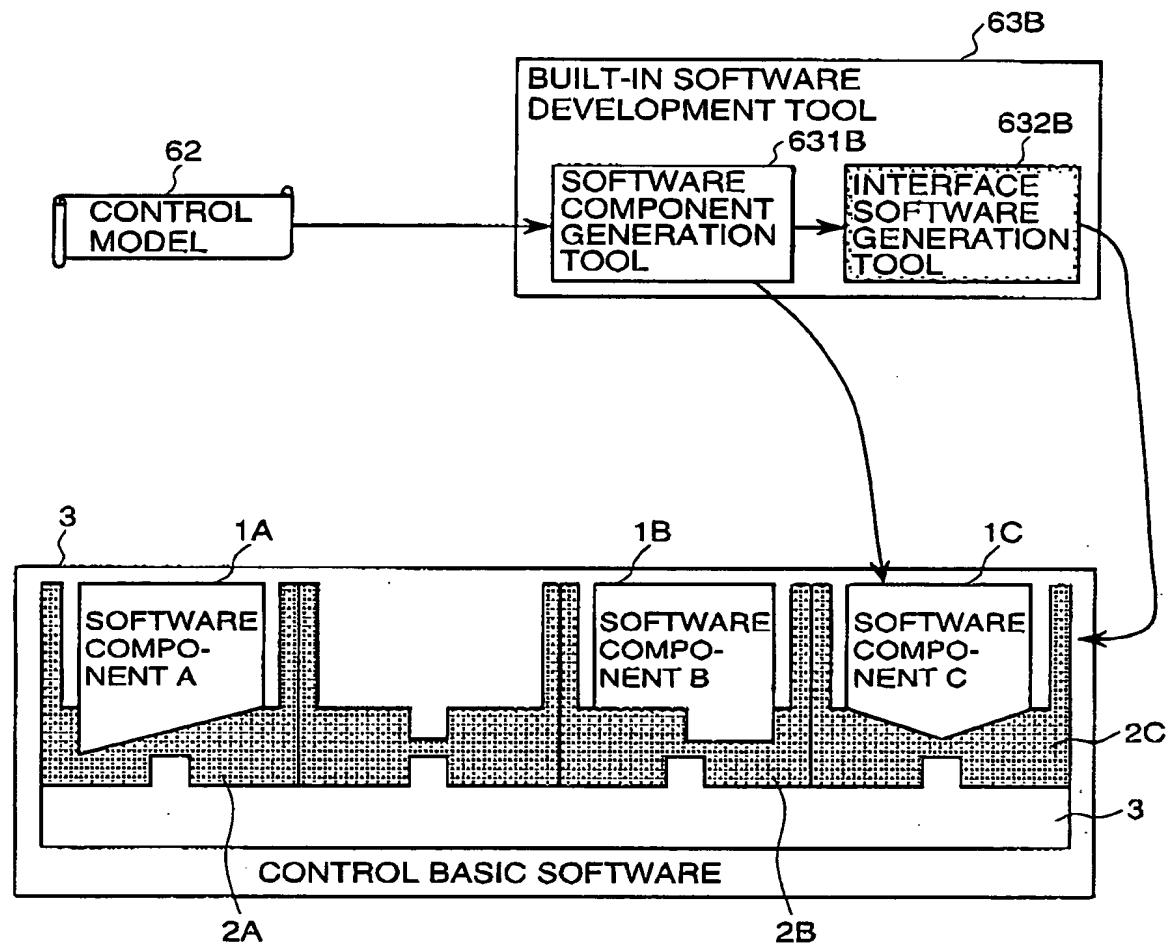
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FIG. 14



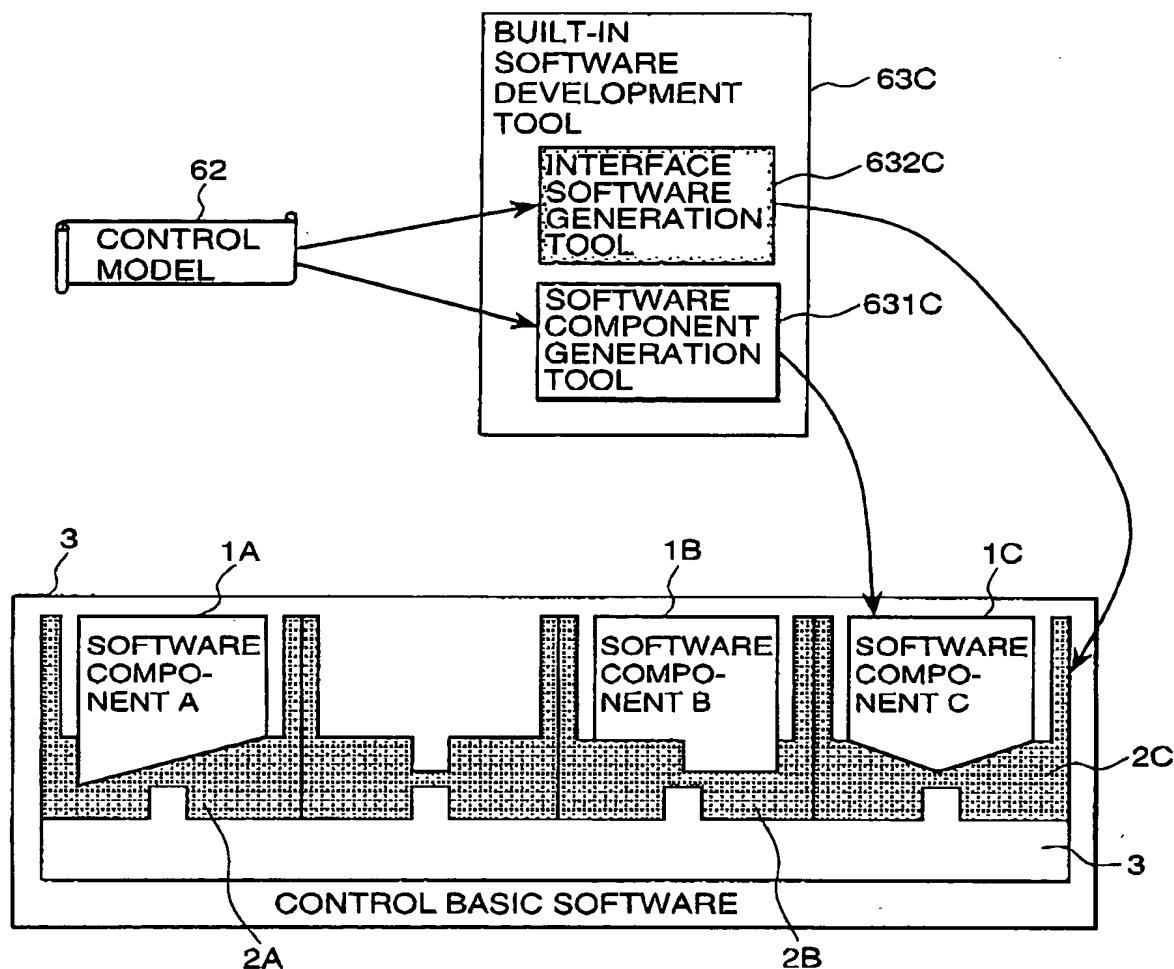
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FIG. 15



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FIG. 16



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FIG. 17

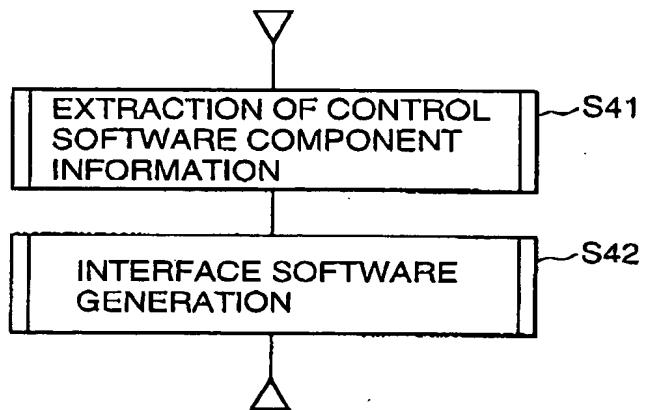
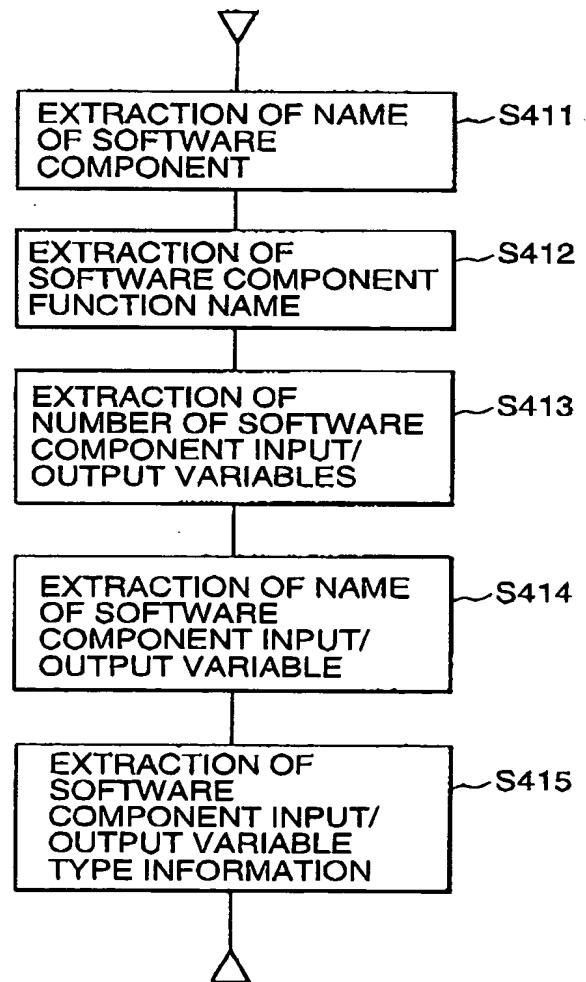


FIG. 18



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FIG. 19

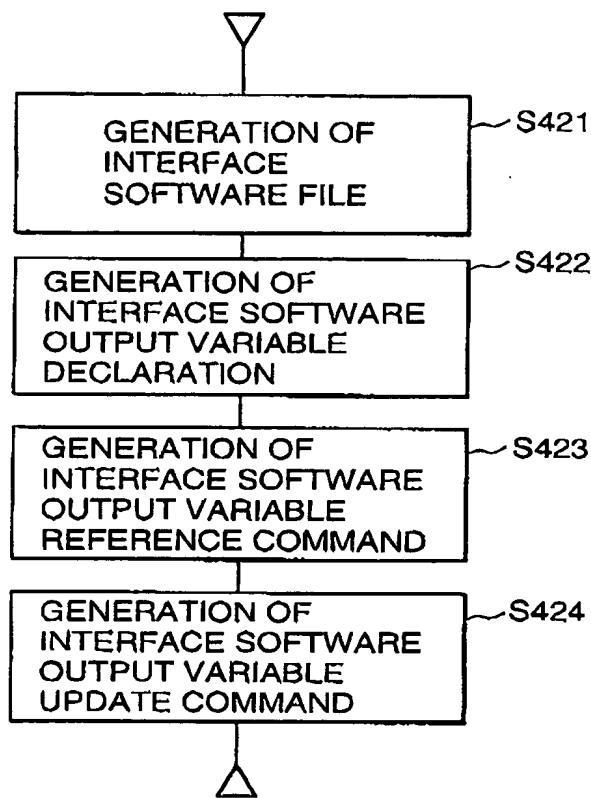
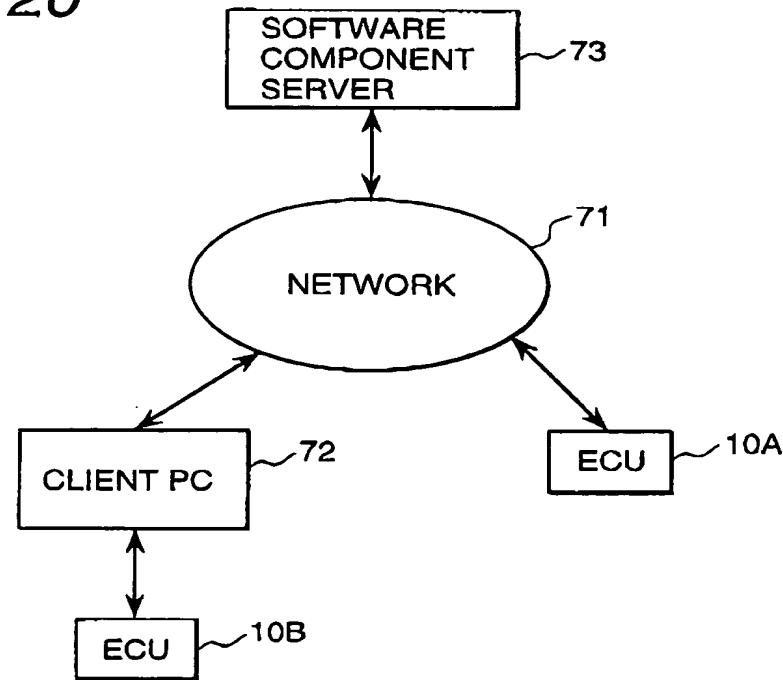


FIG. 20



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FIG. 21

